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| Portefølje 3 |
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| Robotter i Kontekst |

**Robtek 5. Semester**

17. december 2016

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# Methods

First we use the sensor class to find objects, when we find the points, we push them to a vector and store them there, after that, we color the objects in a different shade of gray so we don’t end up storing the objects twice.

# Image searching for objects

# Image for driving.

# Nr. of pixels traversed

The number of pixels traversed total is xxx and the number of pixels during search is xxx and the number of pixels during transportation is xxx